## Name and Surname:

22 December 2006

## **ELE 361**

## Hacettepe University Electrical and Electronics Engineering Department

Midterm II Solutions

	Q1	:
Duration: 100 min.	Q2	•
	Q3	:
	Q4	:
	TOTAL	• •

Q1. (25 pts) Consider the solenoid shown in Fig.1. Over a limited range of displacement x, the coil inductance is given by:  $L(x) = 0.30 + 270 x^2$ , H where, x is in m. For x = 1 cm,

a. Find the instantaneous, average and peak forces acting on the plunger when the coil current is 1A rms at 60 Hz sinusoidal.

b. Find the approximate voltage which must be applied to the coil to cause this current to flow.

c. What is the force for a coil current of 1 A dc, compare with the average force found in part (a).

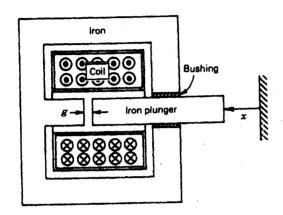


Fig.1. Magnetically operated plunger

Soln (a) 
$$f = \frac{1}{2}i^2\frac{dL}{dt}$$
,  $i(t) = \sqrt{2}\sin \omega t$ ,  $\omega = 2\pi60 \text{ rad/pec}$ 
 $i^2(t) = 2\left(0.5 - 0.5\cos(2\times37)t\right)$ 
 $\frac{dL}{dx} = \frac{d}{dx}\left(0.3 + 270\times^2\right) = 540\times\text{ H/m}$ 
 $f(t, x = 1\text{cm}) = \frac{1}{2}\left(1 - \cos 754t\right)540\times\text{ }$ 
 $f(t) = 2.7 - 2.7\cos 754t$ , Nt. //

For a varies from 0 to 5.4 Nt peak/
at twice the frequency of current and has an average value of 2.7 Nt/

 $f_{\text{en}} = 2.7 + \frac{1}{2.7} + \frac{1}{2.7$ 

$$v(t) = N \frac{d\phi}{dt} = -N \omega \hat{\phi} \sin \omega t, V$$

$$V_{rms} = \frac{N \omega \hat{\phi}}{Vz} = 4.44 f N \hat{\phi}$$

$$T_{e} = -\frac{1}{2} \phi^{2} \frac{dR}{d\beta}$$

$$= -\frac{1}{2} \hat{\phi}^{2} \cos^{2} \omega + 8 \cos^{2} \sin 4 \beta$$

$$= -4 \cos^{2} \hat{\phi}^{2} \cos^{2} \omega + \sin^{2} 4 \beta \qquad (= 17.4 \cos^{2} \omega + \sin^{2} 4 \beta)$$

where 
$$\hat{\phi} = \frac{220}{4.44 \times 50 \times 150} = 0.0066 \text{ Wb}$$

b) 
$$T_{e} = -\frac{4\hat{\phi}_{10}^{2}}{2}(1+\cos 2\omega t) \sin 4(\omega m t + \beta_{0})$$

= 
$$-2\frac{h^2}{h^6}$$
  $\sin 4(\omega_m t_p) + \frac{1}{2} \sin 2(2\omega_m + \omega) + \frac{1}{2} \sin 2(2\omega_m - \omega) + \frac{1}{2} \sin 2(2\omega_m -$ 

c) For 
$$w_m = 0$$
 Te =  $-216 \hat{\phi}^2 \sin 4\beta o$  for  $\beta o \neq 0$ ,  $w_m = \pm \frac{1}{2}w$  Te =  $-106 \hat{\phi}^2 \sin 2\beta o$  Nm 11

b) The coil inductance at x = 0.01m is:  $L(x)| = 0.3 + 2 + 0 \times 0.01^{2}$  x = 0.01 = 327 mH //  $X_{L} = \omega L = 377 \times 0.327 = 21, 5 \Omega.$ Neglecting coil resistance, voltage
to be applied for 1A rms aiment at 60H2;  $V = I X_{L} = 1 \times 123.5 = 123.5 V_{rms} \text{ at } 60 \text{ H}$ 

c)  $f = \frac{1^2}{2}$  540×0.01 = 2.7 Nt// equal to part

A given value of rms are current

will produce an average force

equal to that produced by the same

value of Jc current

1

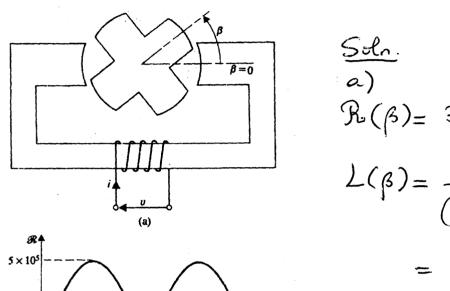
Q2. (25 pts) Figure 2.a illustrates the cross-section of a reluctance motor with four rotor poles. These poles are shaped so that the reluctance of the magnetic circuit is a sinusoidally varying function of  $\beta$ , as illustrated in Fig.2.b. The coil has 150 turns, and negligible resistance. A sinusoidal voltage is applied to the coil terminals of 220 V rms at 50 Hz.

6pt. - a. Find the variation of the self inductance of the coil as a function of  $\beta$ .

Logk. b. Derive an expression for the instantaneous torque developed by the machine.

6 pt. c. Determine the rotor speed(s) for which non-zero average torque can be produced.

3 pt. d. What is the maximum average torque the machine can produce.



 $\frac{3\pi}{4}$ 

Fig.2. The reluctance motor

(b)

10

$$\frac{Soln.}{a)}$$

$$\Re(\beta) = 310^{5} - 210\cos 4\beta$$

$$L(\beta) = \frac{N^{2}}{(3 - 2\cos 4\beta)10^{5}}, H$$

$$= \frac{0.225}{3 - 2\cos 4\beta}, H.$$

$$b) Te = \frac{1}{2} L^{2} \frac{dL}{d\beta}$$

$$v(t) = 22012 \sin \omega t$$

$$i(t) = \frac{1}{L(\beta)} \int v(t)dt = -\frac{1}{\omega L(\beta)} 22012 \cos \omega t$$

$$= -\frac{3 - 2\cos 4\beta}{0.225\omega} 22012 \cos \omega t$$

$$Te = \frac{1}{2} \frac{(3 - 2\cos 4\beta)^{2}}{0.225^{2}\omega^{2}} (22012 \cos \omega t)^{2} \frac{(-8\sin 4\beta)0.225}{(3 - 2\cos 4\beta)^{2}}$$

$$= -\frac{8(22015)^{2}}{2 \times 0.225^{2}\omega^{2}} \cos^{2}\omega t \sin 4\beta \qquad (= 17.43 \cos^{2}\omega t \sin 4\beta)$$

$$= \frac{8(22015)^{2}}{2 \times 0.225^{2}\omega^{2}} \cos^{2}\omega t \sin 4\beta \qquad (= 17.43 \cos^{2}\omega t \sin 4\beta)$$

Q3. (25 pts) The magnetization curve (E<sub>a</sub> vs I<sub>f</sub>) of a separately-excited dc generator is approximated as given below. The generator armature resistance  $r_a = 0.2$  ohm, and the field resistance  $r_f = 20$  ohms.

$$E_a = n_r (a + bI_f) / 1500$$
 where,  
 $a = 7$ ,  $b = 22.5$  for  $0 < I_f \le 2$  A;  
 $a = -32$ ,  $b = 42$  for  $2 < I_f \le 4$  A;  
 $a = -2$ ,  $b = 34.5$  for  $4 < I_f \le 6$  A;  
 $a = 127$ ,  $b = 13$  for  $6 < I_f \le 8$  A.

a. Find the induced armature emf E<sub>a</sub> for the field current of 6.5A, at a speed of 1750 rev/min.

b. For the conditions in part (b), the generator is now loaded, and armature current is measured as  $I_a = 150$  A. The friction and windage loss of the machine is 200 W at 1750 rev/min. What are the percent efficiency and percent voltage regulation of the generator?

$$\frac{\text{Soln. a)}}{5\text{pt.}} = \frac{1750}{1500} \left( \frac{127 + 13 \times 6.5}{1500} \right)$$

$$\frac{\text{Ea}}{1500} = \frac{1750}{1500} \left( \frac{127 + 13 \times 6.5}{1500} \right)$$

b) 
$$N_{r}=1750\text{ rpm}$$
  $E_{a}=246.75 V // I_{a}=150 \text{ A}$   $=$   $V_{t}=E_{a}-r_{a}I_{a}=246.75-0.2 \times 150$   $=$   $246.75-0.2 \times 150$   $=$   $216.75 V // I_{a}=216.75 V // I_{a}=216.$ 

Spt. 
$$P_{cur} = 200W$$
 $P_{cur} = I_a^2 r_a = 4.5 \text{ kW}$ 
 $P_{freld} = I_f^2 r_f = 0.85 \text{ kW}$ 
 $P_{out} = V_t I_q = 32.5 \text{ kW}$ 

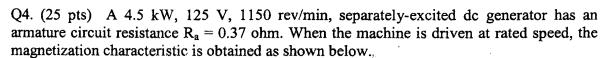
5pt. 
$$7 = \frac{P_{\text{out}}}{P_{\text{out}} + P_{\text{loss}}} = \frac{32.5 \times 100}{32.5 + 0.2 + 4.5 + 0.85}$$

$$= 85.4 \%$$

$$= -\frac{1}{100} = \frac{-100}{100} = \frac{246.75}{100} = \frac{246.75}{100}$$

5pt. Peg. =  $\frac{-\sqrt{k} + Ea}{\sqrt{k}}$  100 =  $\frac{246.75}{216.75}$  100 = 13.8% full box

(12 0/0 wir.t. hoload)



- $|O_p|$ . A. If the field rheostat is adjusted to give a field current of  $I_f = 2 A$ , and the machine is driven at 1000 rev/min,
  - Find the armature induced emf E<sub>a</sub>.
  - What will be the armature terminal voltage V<sub>t</sub> when the load current is at the rated value.
- ASpt. B. The machine is now driven as a shunt dc generator at rated speed, and the field rheostat is adjusted to give a no-load terminal voltage of 135 V.
  - 3 Express armature induced emf E<sub>a</sub> as a function of I<sub>f</sub>.
  - 4 Using the magnetization characteristic of the dc generator, find operating  $E_a$  and  $I_f$  values.
  - 8 What will be the armature terminal voltage V<sub>t</sub>', when it is delivering its rated current?

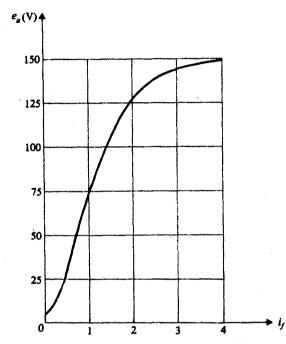


Fig.3. Magnetization characteristic

Soln. A. If = 2A at n= 1000 pm Ea = Kg of wm For If=2A Ea = 126V from magn. ch. at 1150 rpm Thus at 1000 gm:  $E_{a} = \frac{1000}{1150} 126 = 109 V$ JEa Vt = Ea - Ia ra Iarated = 4500 = 36 A

When Ea = 135V, If=2,4A from magni ch. =) Rf = 135/2,4 = 56.202 Ea = (ra+Rf) If = 56.6 If When Ia = 36 A New boad line; Ea = 0,37x36+564 = 13,3+56,6If From magn.cl. & load line intersection: Fa = 127V. Ir=2.05A//

 $\Rightarrow$   $V_{+} = 109 - 0.37 \times 36 = 95.7V$ 

$$V_{t}' = 127 - 0.37 \times 36$$

$$= 114 \, \text{V} / \text{I}.$$

$$I_{L} = I_{9} - I_{f} = 36 - 2.05 = 34 \, \text{A} / \text{I}$$